

Index Theorems for the Stability of Periodic Traveling Waves of KdV Type

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Outline

- 1 Intro to GKdV Stability Theory
- 2 Periodic Case: Spectral Stability
- 3 Computations
- 4 Nonlinear (Orbital) Stability
- 5 Conclusions

Introduction

Consider the KdV equation

$$u_t = u_{xxx} + f(u)_x$$

where $f(u)$ is “nice”. Arise in applications with a variety of nonlinearities.

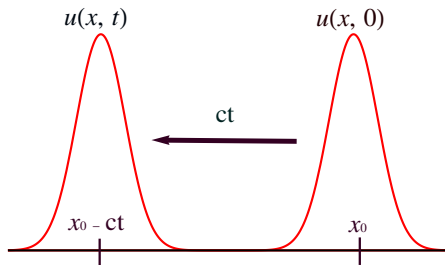
- $f(u) = u^2 \Rightarrow$ KdV equation. Canonical model for weakly dispersive nonlinear unidirectional wave propagation.
- $f(u) = \pm u^3 \Rightarrow$ focusing/defocusing mKdV equation. Arises naturally in plasma physics as a model for ion acoustic perturbations.
- $f(u) = \alpha u^{r+1/2}$ for $r \in (-\frac{1}{2}, \frac{1}{2})$... has been derived in several plasma physics models.

Also interesting for mathematical study: $f(u) = u^5$ is L^2 critical, and KdV and mKdV are completely integrable PDE!

Traveling Waves of form $u(x, t) = \bar{u}(x + ct)$ are basic structures in nonlinear waves!

- Characteristics:

- (1) Constant velocity c
- (2) Same shape and profile!



∴ Traveling wave profile \bar{u} is STATIONARY solution of PDE

$$u_t = u_{xxx} + f(u)_x - cu_x,$$

i.e. solves ODE

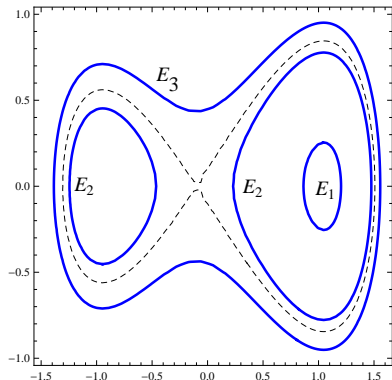
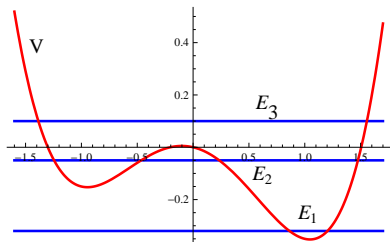
$$u''' + f(u)' - cu' = 0.$$

After one integration, this is a HAMILTONIAN ODE!!!

Wave profile u must satisfy ODE

$$\frac{u_x^2}{2} = E - \underbrace{F(u) - \frac{cu^2}{2}}_{V(u;a,c)} + au, \quad F' = f$$

where $a, E \in \mathbb{R}$ depend on boundary conditions imposed.



Summary of \exists theory

Solitary Waves:

- If $\bar{u}(x) \rightarrow \text{const.}$ when $x \rightarrow \pm\infty$, have “Solitary wave”.
- In this case, a and E fixed by b.c.’s at $\pm\infty$, so have two parameter family of traveling waves:

$$\bar{u}(x + x_0 - ct; c).$$

Periodic Waves:

- If $\bar{u}(x + T) = \bar{u}(x)$ for some $T > 0$, have “periodic wave”.
- In this case, a and E are “free”, so have four parameter family of traveling waves:

$$\bar{u}(x + x_0 - ct; a, E, c), \quad \text{period } T = T(a, E, c).$$

- In special cases, \bar{u} can be expressed in terms of elliptic functions. We make no use of this extra structure in our analysis...

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Solitary Wave Stability Theory:

Linearization of gKdV flow about solitary wave with $\bar{u}(x) \rightarrow 0$ as $x \rightarrow \pm\infty$:

$$-v_t = \partial_x \underbrace{(-\partial_x^2 - f'(\bar{u}) + c)}_{\mathcal{L}[\bar{u}]} v, \quad v \in L^2(\mathbb{R}).$$

Seek separated solution $v(x, t) = e^{-\lambda t} v(x)$ leads to spectral problem

$$\partial_x \mathcal{L}[\bar{u}] v = \lambda v.$$

Spectral stability iff $\sigma(\partial_x \mathcal{L}[\bar{u}]) = \sigma_{\text{ess}}(\partial_x \mathcal{L}[\bar{u}]) \cup \sigma_p(\partial_x \mathcal{L}[\bar{u}]) \subset i\mathbb{R}$.

Essential Spectrum: Linear dispersion relation about background $\bar{u} \equiv 0$ state is

$$ik(k^2 - f'(0) + c) = \lambda \Rightarrow \sigma_{\text{ess}}(\partial_x \mathcal{L}[\bar{u}]) = i\mathbb{R}.$$

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Point Spectrum: Eigenvalues of $\partial_x \mathcal{L}[\bar{u}]$, acting on $L^2(\mathbb{R})$, determined by roots of “Evans Function” (transmission coefficient) $D(\lambda)$.

- $D(\lambda)$ detects intersections of stable mfld. at $+\infty$ and unstable mfld at $-\infty$.
- Complex analytic in λ .
- Roots agree in location and (algebraic) multiplicity of e.v.'s of $\partial_x \mathcal{L}[\bar{u}]$.

Fact 1

- 1 $\text{sign}(D(\lambda)) = 1$ for $\lambda \gg 1$.
- 2 For some constant $A > 0$,

$$D(\lambda) = A \left(\partial_c \int_{\mathbb{R}} u(x; c)^2 dx |_{\bar{u}} \right) \lambda^2 + \mathcal{O}(|\lambda|^3).$$

Thus, have spectral instability if $\partial_c \int_{\mathbb{R}} u(x; c)^2 dx < 0$ at \bar{u} .

FACT 2: [Pego& Weinstein 1992] $0 \leq n_-(\partial_x \mathcal{L}[\bar{u}]) \leq n_-(\mathcal{L}[\bar{u}])$.

FACT 3: For solitary waves, $n_-(\mathcal{L}[\bar{u}]) = 1$.

Proof: \bar{u}' satisfies $\mathcal{L}[\bar{u}]\bar{u}' = 0$ and has only one root on \mathbb{R} . Sturm Liouville Theory \Rightarrow 0 is second eigenvalue of $\mathcal{L}[\bar{u}]$.

\therefore all unstable eigenvalues must be real!

\therefore Spectral stability iff $\partial_c \int_{\mathbb{R}} u(x; c)^2 dx > 0$ at \bar{u} .

Further, Fact 3 \Rightarrow condition necessary/sufficient for nonlinear (orbital) stability!

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Periodic Case?

Periodic Case is much more complicated:

- (1) “More” of them: 4 parameter family, compared to 2 parameter family of solitary waves.
- (2) More general classes of perturbations available:
 - (a) Co-periodic = $L^2(\mathbb{R}/T\mathbb{Z})$.
 - (b) Sub-harmonic = $L^2(\mathbb{R}/nT\mathbb{Z})$, $n \in \mathbb{N}$, $n > 1$.
 - (c) Localized = $L^2(\mathbb{R})$... Most Physical!
- (3) Structure of spec.: may be only eigenvalues, may be only essential spec... depends on class of perturbations.
- (4) $n_-(\mathcal{L}[\bar{u}])$ can be *arbitrarily large* (or “uncountable”) depending on class of perturbations.

Periodic Stability Theory

- Let \bar{u} be T -periodic stationary solution of the nonlinear PDE

$$u_t = u_{xxx} + f(u)_x - cu_x.$$

Consider a perturbation of \bar{u} : $\psi(x, t) = \bar{u}(x) + \varepsilon v(x, t)$, $v \in X$.

$$\Rightarrow \partial_x \underbrace{\left(-\partial_x^2 - f'(\bar{u}) + c \right)}_{\mathcal{L}[\bar{u}]} v = -v_t$$

Decompose $v(x, t) = e^{-\lambda t} v(x)$ so v solves the spectral problem

$$\partial_x \mathcal{L}[u] v = \lambda v$$

considered on X .

Spectral stability to X -perturbations $\iff \text{spec}_X(\partial_x \mathcal{L}[u]) \subset \mathbb{R}i$.

Goal: analyze spectral problem

$$\partial_x \mathcal{L}[\bar{u}]v = \lambda v, \quad v \in X. \quad (\star)$$

What is structure of $\text{spec}_X(\partial_x \mathcal{L}[u])$?

(1) If $X = L^2(\mathbb{R}/nT\mathbb{Z})$, then

$$\text{spec}_X(\partial_x \mathcal{L}[u]) = \text{spec}_{X,p}(\partial_x \mathcal{L}[u])$$

$\Rightarrow (\star)$ is an eigenvalue problem!!

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Localized Perturbations: $X = L^2(\mathbb{R})$

- To see this, write spectral problem as first order system

$$Y'(x, \lambda) = \mathbf{H}(x, \lambda)Y(x, \lambda).$$

- Period Map (Monodromy): $\mathbf{M}(\lambda) = \Phi(T, \lambda)$, where $\Phi(x, \lambda)$ is the matrix solution such that $\Phi(0, \lambda) = \mathbf{I}$. Thus, $\mathbf{M}(\lambda)$ is an operator such that

$$\mathbf{M}(\lambda)v(x, \lambda) = v(x + T, \lambda)$$

for any $x \in \mathbb{R}$ and vector solution $v(x, \lambda)$. For simplicity, assume that $v(x, \lambda)$ satisfies

$$\mathbf{M}(\lambda)v(x, \lambda) = \mu v(x, \lambda)$$

Then for all $n \in \mathbb{Z}$ have

$$v(NT, \lambda) = \mathbf{M}(\lambda)^N v(0, \lambda) = \mu^N v(0, \lambda)$$

\Rightarrow if $v(x, \lambda) \rightarrow 0$ as $x \rightarrow +\infty$, then $\lim_{x \rightarrow +\infty} |v(x, \lambda)| = +\infty$.



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\Rightarrow if $v(x, \lambda) \rightarrow 0$ as $x \rightarrow +\infty$, then $\lim_{x \rightarrow -\infty} |v(x, \lambda)| = +\infty$.

Best you can hope for is for v to be uniformly bounded, i.e. $|\lambda| = 1$.

- Gives characterization of (continuous) spectrum:

$$\lambda \in \text{spec}(\partial_x \mathcal{L}[u]) \iff \sigma(\mathbf{M}(\lambda)) \cap S^1 \neq \emptyset.$$

Following Gardner then, we define

$$D(\lambda, e^{i\kappa}) = \det(\mathbf{M}(\lambda) - e^{i\kappa} \mathbf{I}).$$

Then $\lambda \in \text{spec}(\partial_x \mathcal{L}[u]) \iff D(\lambda, e^{i\kappa}) = 0$ for some $\kappa \in \mathbb{R}$.

- Moreover,

$$\text{spec}_{L^2(\mathbb{R})}(\partial_x \mathcal{L}[u]) = \bigcup_{\kappa \in [-\pi, \pi)} \{\lambda \in \mathbb{C} : D(\lambda, e^{i\kappa}) = 0\}.$$

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Remark:

If $\kappa \in 2\pi\mathbb{Q}$, then bounded solution of

$$\mathbf{M}(\lambda)v = e^{i\kappa}v$$

is nT periodic for some $n \in \mathbb{N}$, i.e. $\lambda \in \sigma_{L^2(\mathbb{R}/nT\mathbb{Z})}(\partial_x \mathcal{L}[\bar{u}])$.

$$\Rightarrow \operatorname{spec}_{L^2(\mathbb{R})}(\partial_x \mathcal{L}[u]) = \overline{\bigcup_{n \in \mathbb{N}} \operatorname{spec}_{L^2(\mathbb{R}/nT\mathbb{Z})}(\partial_x \mathcal{L}[u])}.$$

\therefore spec. stable in $L^2(\mathbb{R})$ iff spec. stable in $L^2(\mathbb{R}/nT\mathbb{Z}) \forall n \in \mathbb{N}$.

Analysis of Evans fn.

\exists theory gives *a lot* of information about spectrum at $\lambda = 0$.

- Have 4-dim manifold

$$\mathcal{M} = \{u(x + x_0 - ct; a, E, c)\}$$

of stationary solutions of gKdV

$$u_t - u_{xxx} - f(u)_x + cu_x = 0.$$

- Diff. Geometry \Rightarrow equation

$$(\partial_t - \partial_x \mathcal{L}[\bar{u}])v = 0$$

defines tan. space of \mathcal{M} at fixed solution \bar{u} .

- Tan. space at \bar{u} generated by variations:

$$\mathcal{T}_{\bar{u}}(\mathcal{M}) = \text{span}\{u_x, u_a, u_E, -tu_x + u_c\}$$

- Follows that (formally)

$$\partial_x \mathcal{L}[u]\{u_x, u_a, u_E\} = 0, \quad \partial_x \mathcal{L}[u]u_c = -u_x.$$

Periodic Stability Theory

\therefore have full set of (formal) solutions to ODE

$$\partial_x \mathcal{L}[u]v = 0.$$

Moreover, \bar{u}_x is T -periodic... follows that

$$D(0, 1) = \det(\mathbf{M}(0) - \mathbf{I}) = 0.$$

Want to find curve $\kappa \rightarrow \lambda(\kappa)$ defined in neighborhood of $(\lambda, \kappa) = (0, 0)$ such that

$$D(\lambda(\kappa), e^{i\kappa}) = \det(\mathbf{M}(\lambda(\kappa)) - e^{i\kappa}) = 0.$$

Would be easy if we could use implicit function theorem, i.e. if

$$\partial_\lambda D(\lambda, 1)|_{\lambda=0} \neq 0.$$

Evaluate of $\partial_\lambda D(\lambda, 1)|_{\lambda=0}$

- At $\lambda = 0$, $\{u_x, u_a, u_E\}$ provides three linearly independent solutions of the *formal* differential equation

$$\partial_x \mathcal{L}[u]v = 0.$$

Thus, can explicitly construct monodromy matrix at $\lambda = 0$.

- By analyticity of $\mathbf{M}(\lambda)$, have

$$\mathbf{M}(\lambda) = \mathbf{M}(0) + \lambda \mathbf{M}_\lambda(0) + \mathcal{O}(|\lambda|^2)$$

We use perturbation theory to find $\mathbf{M}_\lambda(\lambda)$

- Variation of parameters formula yields first order variation in u_a and u_E columns. Moreover, u_c solves

$$\partial_x \mathcal{L}[u]u_c = -u_x$$

Follows that $-u_c$ gives first order λ -variation in translation (u_x) direction!!!! Thus, we have constructed $\mathbf{M}_\lambda(0)$.

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$$\partial_x \mathcal{L}[u]u_c = -u_x$$

Follows that $-u_c$ gives first order λ -variation in translation (u_x) direction!!!! Thus, we have constructed $\mathbf{M}_\lambda(0)$.

Asymptotic Expansion of $D(\lambda, 1)$

- Taking determinants then, we have

$$\frac{d}{d\lambda} D(\lambda, 1) = \det (\mathbf{M}(0) + \lambda \mathbf{M}_\lambda(0) - I + \mathcal{O}(|\lambda|^2)) \Big|_{\lambda=0} = 0$$

\Rightarrow Implicit Function Theorem fails!!!!

- We need to determine next order term $\mathbf{M}_{\lambda\lambda}(0)$. Can be done by using variation of parameters again!

Asymptotic Expansion for $D(\lambda, 1)$

- Ugly algebra yields

$$D(\lambda, 1) = -\frac{1}{2} \underbrace{\frac{\partial(T, M, P)}{\partial(a, E, c)}}_{\{T, M, P\}_{a, E, c}} \lambda^3 + \mathcal{O}(|\lambda|^4).$$

where T = period and M and P refer to the mass and momentum:

$$M = \int_0^T u(x) dx \quad P = \int_0^T u(x)^2 dx.$$

M and P are conserved quantities of the gKdV flow!

- Thus, $D(\lambda, 1) = \mathcal{O}(|\lambda|^3)$ and hence more care is needed to use the implicit function theorem.
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- Continuing above computations, local analysis around $(\lambda, \kappa) = (0, 0)$ yields

$$D(\lambda, e^{i\kappa}) = i\kappa^3 + \frac{i\kappa\lambda^2}{2} (\{T, P\}_{E,c} + 2\{M, P\}_{a,E}) - \frac{\lambda^3}{2} \{T, M, P\}_{a,E,c} + \mathcal{O}(|\lambda|^4 + \kappa^4)$$

where the notation $\{f, g\}_{x,y}$ is used for two-by-two Jacobians.

- Defining $z = \frac{i\kappa}{\lambda}$, we see z must be a root of

$$P(z) = -z^3 + \frac{z}{2} (\{T, P\}_{E,c} + 2\{M, P\}_{a,E}) - \frac{1}{2} \{T, M, P\}_{a,E,c}$$

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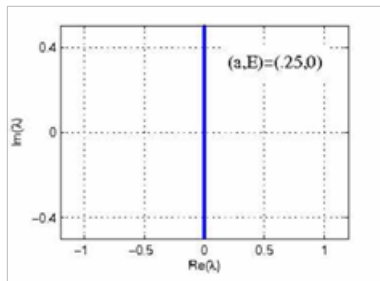
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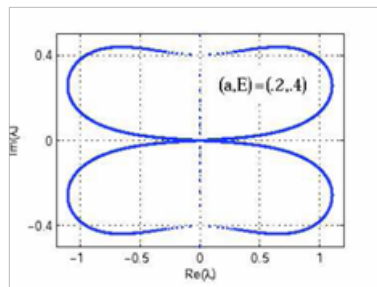
and hence have modulational stability when P has three real roots!

Define

$$\Delta_{MI} := \frac{1}{2} (\{T, P\}_{E,c} + 2\{M, P\}_{a,E})^3 - \frac{27}{4} \{T, M, P\}_{a,E,c}^2.$$



$$\Delta_{MI} > 0$$



$$\Delta_{MI} < 0$$

Yields “normal form” for spectrum near origin for gKdV equations!

Index Δ_{MI} detects instabilities to “long-wavelength” perturbations, i.e. to \tilde{T} -periodic perturbations with

$$0 < |T - \tilde{T}| \ll 1.$$

Such instabilities sometimes called “modulational” or “side-band”.

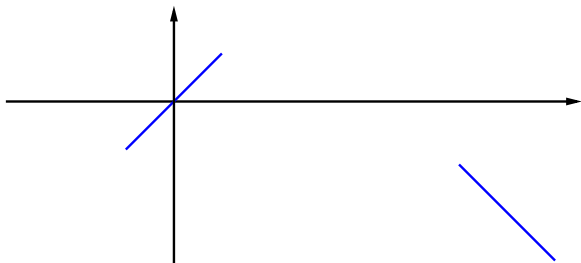
Can also use above computations to detect “co-periodic” ($\kappa = 0$) instabilities, i.e. stabilities in $L^2(\mathbb{R}/T\mathbb{Z})$.

Recall, from above, that $D(\lambda, 1) = -\frac{1}{2}\{T, M, P\}_{a,E,c}\lambda^3 + \mathcal{O}(|\lambda|^4)$. Also, can prove that

$$\lim_{\lambda \rightarrow \infty} \text{sign}(D(\lambda, 1)) < 0$$

Yields orientation index

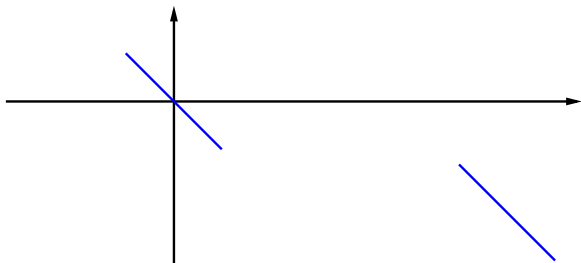
$$\lim_{\lambda \rightarrow 0^+} \text{sign}(D(\lambda, 1)) \lim_{\lambda \rightarrow \infty} \text{sign}(D(\lambda, 1)) = \text{sign}(\{T, M, P\}_{a,E,c}).$$



If $\{T, M, P\}_{a,E,c} < 0$, then $D(\lambda, 1) = 0$ for some $\lambda > 0$.

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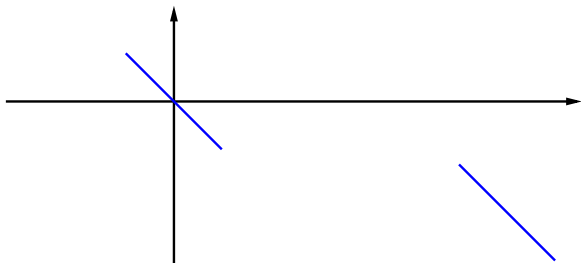


If $\{T, M, P\}_{a,E,c} > 0$, then $D(\lambda, 1) < 0$ for all $\lambda > 0$?

Yes, if for $\mathcal{L}[u]$ considered on $L^2(\mathbb{R}/T\mathbb{Z})$, $n_-(\mathcal{L}[u]) = 1$. (Same argument as in Solitary wave case!)

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Using standard asymptotic methods, can show that in "homoclinic limit"

$$\{T, M, P\}_{a,E,c} \sim -T_E M_a P_c$$

and where $T_E > 0$ (clearly) and $M_a < 0$ (computation).

Thus, in homoclinic limit,

$$\text{sign}(\{T, M, P\}_{a,E,c}) = \text{sign}(P_c) = \text{sign}\left(\partial_c \int_0^T u^2 dx\right).$$

Moreover, by scaling, have

$$\text{sign}(P_c) = \text{sign}\left(\frac{2}{pc} - \frac{1}{2c}\right) = \text{sign}(4 - p).$$

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Computation?

- OK, so you have an expression which “determines” when a particular wave is modulationally stable..... can you compute it?!
- YES!!!
 - (1) For power-law nonlinearities ($f(u) = u^{p+1}$) with $p \in \mathbb{N}$, can determine explicit formula for MI index in terms of moments of the underlying wave.
 - (2) For non-power-law, must rely on numerics..... but at least you now have a determined quantity to do numerics on!

Modulational Theory for KdV

- In case of KdV

$$u_t = u_{xxx} + \left(\frac{u^2}{2} \right)_x,$$

can express conserved quantities and period as integrals of closed cycles over a Riemann surface, and hence we can compute MI index using elliptic function calculations (Picard-Fuchs system).

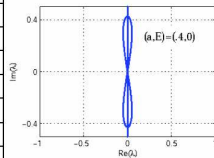
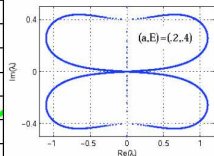
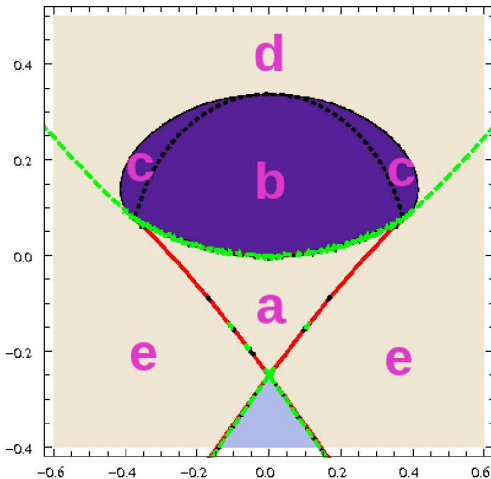
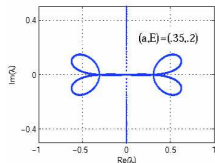
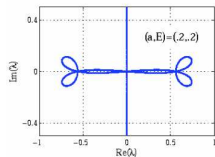
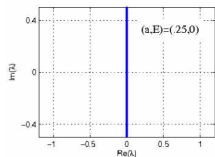
- Get

$$\Delta_{MI} = C_0 \cdot \frac{N^2}{\text{disc}(E - V(\cdot; a, E, c))}$$

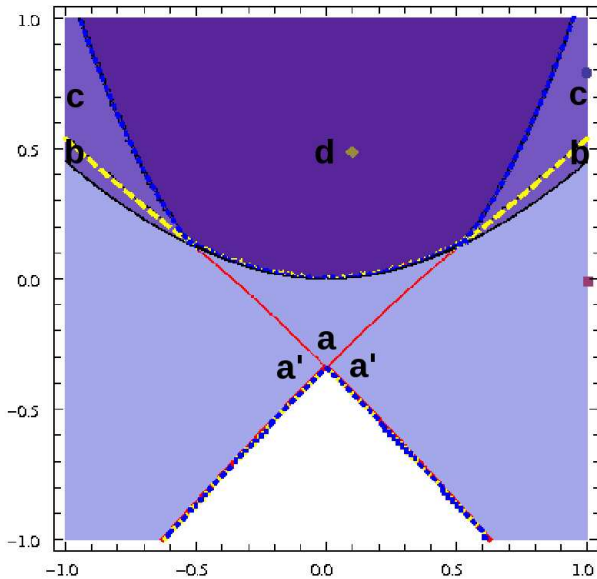
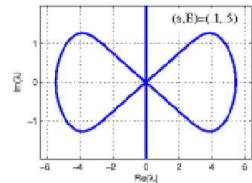
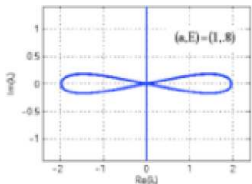
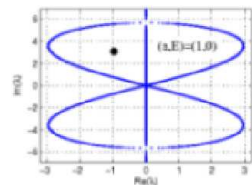
where $C_0 > 0$.

- Notice $\text{disc}(E - V(\cdot; a, E, c)) > 0$ iff the corresponding solution is periodic, so all periodic waves of KdV are modulationally stable!!!!

Modulational Theory for mKdV $f(u) = u^3$ w/ $c > 0$



L^2 -Critical KdV $f(u) = u^5$ (with positive wavespeed)



Nonlinear (Orbital) Stability

Q: Does spectral stability \Rightarrow Orbital Stability?

- True for solitary waves!
- Depends on class of perturbations for periodic case!!

In periodic case, if consider perturbations in...

- $L^2(\mathbb{R}/T\mathbb{Z})$, then

$$0 \leq n_-(\partial_x \mathcal{L}[\bar{u}]) \leq n_-(\mathcal{L}[u]) = 1 \text{ or } 2,$$

so, sometimes, spec. stable \Rightarrow orbital stable (same argument from solitary wave case).

- $L^2(\mathbb{R}/nT\mathbb{Z})$, then

$$n \leq n_-(\mathcal{L}[\bar{u}]) \leq n + 1$$

so solitary wave argument goes out window!

- For KdV/mKdV, can work around this for any $n \in \mathbb{N}$!
- KdV/mKdV proof follows “multi-soliton” stability approach.
- Nothing known outside integrable context...
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Result of Deconinck & Kapitula: $\forall n \in \mathbb{N}$,

$$k_u^+(n) + k_i^-(n) = n_- (\mathcal{L}[\bar{u}]|_{H^1(n)}) - n(D)$$

where

- (a) $k_u^+(n) = \#$ Unstable e.v.'s of $\partial_x \mathcal{L}[\bar{u}]$ on $L^2(\mathbb{R}/nT\mathbb{Z})$ w/
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- (b) $k_i^-(n) = \#$ Purely imaginary e.v.'s of $\partial_x \mathcal{L}[\bar{u}]$ on $L^2(\mathbb{R}/nT\mathbb{Z})$ with
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$$v \in N(\partial_x \mathcal{L}[u] - \lambda), \quad \kappa(v) := \langle v, \mathcal{L}[u]v \rangle_{L^2([0, nT])} \cdot$$

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Main Point: If $k_u^+(n) > 0$ for some n , have instability... what if $= 0$?

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Theorem:[Bronski, M.J., Kapitula (to appear)] We have

$$k_u^+(n) + k_i^-(n) = 2n - p(\partial^2 K(\bar{u}))$$

where $K = K(a, E, c)$ is the classical action (in sense of action-angle variables) of the traveling wave ODE

$$\frac{u_x^2}{2} = E - V(u; a, E, c),$$

and $p(A)$ denotes the number of positive eigenvalues of a given matrix A .

Here $K(a, E, c) = \oint_{\Gamma} p \, dq = \oint_{\Gamma} \sqrt{E - V(u; a, E, c)} \, du$ is a *generating function* for the conserved quantities of the gKdV flow:

$$K_a = M, \quad K_E = T, \quad K_c = P.$$

So, $\partial^2 K(\bar{u})$ is expressed in terms of derivatives of T, M, P with respect to (a, E, c) .

In particular, for $f(u) = u^p$ can express $p(\partial^2 K(\bar{u}))$ in terms of moments of the wave \bar{u} itself!

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The major steps:

- (1) $n(\mathcal{L}[\bar{u}]|_{H^1(n)}) = n(\mathcal{L}[\bar{u}]) + \text{"fudge factor"}$.
- (2) $n(\mathcal{L}[\bar{u}]) = 2n - 1 + n_-(T_E)$... so unstable e.v.'s may be complex!!!
- (3) Determine $n_-(D)$... relates to Jordan co-periodic Jordan block at $\lambda = 0$.

Proofs are new to literature, but based on VERY classical ideas.

Step 1: Relate $n_-(\mathcal{L}[\bar{u}]|_{H^1(n)})$ and $n_-(\mathcal{L}[\bar{u}])$

Lemma: Spse. T is invertible, bounded below with compact resolvent. Let S be a subspace with $\dim(S) = d$. Then

$$n_-(T|_S) + n_-(T^{-1}|_{S^\perp}) = n_-(T).$$

- $(H^1(n))^\perp = \text{span}(1)$, so

$$n_-(\mathcal{L}^{-1}(H^1(n))^\perp) = n_-(\langle 1, \mathcal{L}^{-1}(1) \rangle)$$

- Traveling waves satisfy

$$u_{xx} + f(u) - cu = a \quad \Rightarrow \quad \mathcal{L}u_a = 1, \quad \mathcal{L}u_E = 0.$$

- Thus (since $T_E u_a - T_a u_E$ is T -periodic),

$$\langle 1, \mathcal{L}^{-1}(1) \rangle = \int_0^T \left(u_a - \frac{T_a}{T_E} u_E \right) dx = \frac{\{T, M\}_{a,E}}{T_E}.$$

Step 1: Relate $n_-(\mathcal{L}[\bar{u}]|_{H^1(n)})$ and $n_-(\mathcal{L}[\bar{u}])$

Lemma: Spse. T is invertible, bounded below with compact resolvent. Let S be a subspace with $\dim(S) = d$. Then

$$n_-(T|_S) + n_-(T^{-1}|_{S^\perp}) = n_-(T).$$

- $(H^1(n))^\perp = \text{span}(1)$, so

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Step 2: Compute $n_-(\mathcal{L})$

Notice $\mathcal{L} = -\partial_x^2 - f'(u) + c$ is a linear Schrodinger operator w/ periodic coefficients.

Facts: Considered as an operator on $L^2(\mathbb{R}/nT\mathbb{Z})$,

- Spec. of \mathcal{L} determined by Floquet discriminate $k(\lambda)$:

$$\lambda \in \text{spec}(\mathcal{L}) \text{ iff } k(\lambda) = 2.$$

- Translation invariance of gKdV $\Rightarrow \mathcal{L}u' = 0 \Rightarrow k(0) = 2$.
- u' has $2n$ roots on $[0, nT) \Rightarrow$ Sturm Liouville Theory says zero is either n^{th} or $(n+1)$ st eigenvalue of \mathcal{L} .
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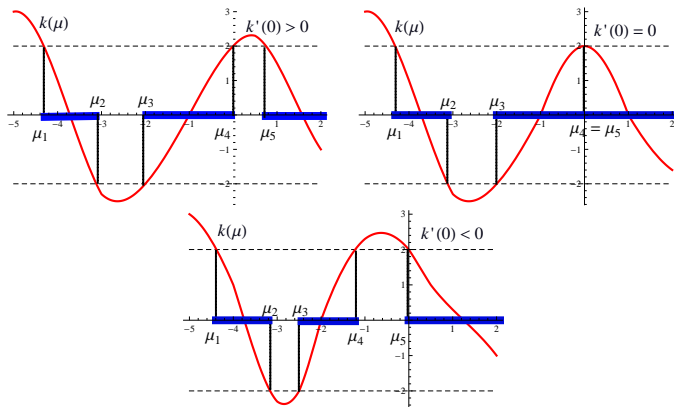
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Step 2: Compute $n_-(\mathcal{L})$ (Cont.)



Fact: $\text{sign}(k'(0)) = \text{sign}(T_E)$.

$$\therefore n_-(\mathcal{L}) = 2n - 1 + n_-(T_E).$$

Follows that

$$\begin{aligned}n_-(\mathcal{L}|_{H^1(n)}) &= n_-(\mathcal{L}) - n_-(\mathcal{L}^{-1}|_{H^1(n)^\perp}) \\ &= 2n - 1 + n_-(T_E) - n_-(T_E\{T, M\}_{a,E}).\end{aligned}$$

Fact: Recall, D comes from Jordan block...

$$n_-(D) = n_-(\{T, M\}_{a,E}\{T, M, P\}_{a,E,c}).$$

So, by "Jacobi-Sturm rule",

$$\begin{aligned}n_-(\mathcal{L}|_{H^1(n)}) - n_-(D) &= 2n - \rho \begin{pmatrix} T_E & T_a & T_c \\ M_E & M_a & M_c \\ P_E & P_a & P_c \end{pmatrix} \\ &= 2n - \rho(\partial \langle T, M, P \rangle (a, E, c)) \\ &= 2n - \rho(\partial^2 K(a, E, c)).\end{aligned}$$

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Conclusions:

- Have presented new set of techniques to analyze stability of periodic waves to more general classes of perturbations.
- Techniques can be used in variety of other problems:
 - ① Ideally, want traveling wave ODE to be completely integrable (gBBM, NLS, etc.).
 - ② Transverse instability analysis.
 - ③ Rigorous justifications of Whitham modulation theory (Formal physical theory for modulational instabilities).

Thank you!