

# Rigorous Stability Theory for Nonlinear Modulated Waves (Justification of the Physicists Intuition)

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Joint work with Jared Bronski (UIUC) and Kevin Zumbrun (IU)

# Outline

- 1 Intro to Stability Theory
- 2 Modulated gKdV Waves
- 3 Rigorous Periodic Stability Theory
- 4 Formal (Whitham) Theory
- 5 Computations
- 6 Conclusions

Working definition of stability in ODE/PDE:

*A solutions ability to persist when subject to slight perturbation*

- Practically important: Unstable solutions do not (naturally) manifest in physical situations, except possibly as transient phenomena.
- Discriminates between physical solutions and mathematical oddities.
- Example: In a mathematical pendulum, the stationary solution  $\theta = 0$  is stable, while  $\theta = \pi$  is unstable .... how do we see this?

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# Introduction

- The equation for an (undamped) mathematical pendulum is

$$\partial_t^2 \theta + \sin(\theta) = 0.$$

Clearly  $\theta_0 = 0$  and  $\theta_0 = \pi$  solve this equation. Consider a nearby solution

$$\psi = \theta_0 + \varepsilon \theta_1 + \mathcal{O}(\varepsilon^2), \quad |\varepsilon| \ll 1$$

and note by Taylor expansion we have

$$\partial_t^2 (\theta_0 + \varepsilon \theta_1) + (\sin(\theta_0) + \varepsilon \cos(\theta_0) \theta_1) = \mathcal{O}(\varepsilon^2)$$

The  $\mathcal{O}(1)$  equation is clearly satisfied, and  $\mathcal{O}(\varepsilon)$  equation reads

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- If  $\theta_0 = 0$ , the linearized equation reads

$$\partial_t^2 \theta_1 + \theta_1 = 0$$

which has solutions  $\theta_1(t) = A \cos(t) + B \sin(t)$ , and hence nearby solutions oscillate around original stationary solution.

- If  $\theta_0 = \pi$ , linearized equation reads

$$\partial_t^2 \theta_1 - \theta_1 = 0$$

which has solutions  $\theta_1(t) = Ae^t + Be^{-t}$ , and hence nearby solutions exponentially diverge from  $\theta_0$ .

- Therefore,  $\theta_0 = \pi$  is (linearly) unstable while  $\theta_0 = 0$  is (linearly) stable.

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# Introduction

- Stability is inherently a physical issue....

- (1) By understanding of mechanism behind instability, one may be able to *stabilize* the solution!

Example: In the pendulum example above, the unstable solution  $\theta_0 = \pi$  can be stabilized by addition of an appropriate periodic forcing term:

$$\partial_t^2 \theta + \sin(\theta) = \beta \cos(t) \sin(\theta).$$

- (2) Helps us understand how solutions of our approximate model actually simulate real life.

Example: Light pulses through a fiber optic wire and the single-particle wavefunction in a Bose–Einstein condensate are modeled by the GrossPitaevskii equation (nonlinear Schrödinger equation)

$$i\psi_t + \psi_{xx} + \psi|\psi|^2 = 0,$$

but this equation does not take into effect impurities or higher order nonlinear effects in the wire. Will a solution of this simplified model persist under the influence of these defects?

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- Physicists often have a fantastic (and correct!) intuition about which solutions of a given model are stable, and which are unstable.
- As mathematicians though, we would like to develop a theory which makes this intuition rigorous!
- Example: It is well known in the physics/engineering community that solutions of a scalar reaction-diffusion equation

$$u_t + u_{xx} = f(u)$$

which satisfy  $\lim_{x \rightarrow \pm\infty} u(x, t) = 0$  are stable iff they are monotone. Thus, fronts are stable but pulses are not.

- How do we understand this as mathematicians?

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- Let  $u = u(x)$  satisfy  $\lim_{x \rightarrow \pm\infty} u_x(x, t) = 0$  and

$$u_t = u_{xx} + f(u)$$

- Consider “nearby” solution  $w(x, t) = u(x) + \varepsilon v(x, t)$ ,  $v \in L^2(\mathbb{R})$

$$\Rightarrow v_t = v_{xx} + f'(u)v.$$

- Decompose  $v(x, t) = e^{\mu t} v(x)$ ,  $\mu \in \mathbb{C}$ :

$$\Rightarrow v_{xx} + f'(u)v = \mu v$$

- If  $u$  is monotone, can show  $\text{spec}(\partial_x^2 + f'(u)v) \subset (-\infty, 0]$  and hence perturbations remain bounded in time!
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- The purpose of this talk is to consider the stability of spatially periodic waves of the generalized Korteweg-de Vries (gKdV) equation

$$u_t = u_{xxx} + f(u)_x$$

where  $f$  is “nice”. Arise in applications with a variety of nonlinearities.

- $f(u) = u^2 \Rightarrow$  KdV equation. Canonical model for weakly dispersive nonlinear unidirectional wave propagation.
- $f(u) = \pm u^3 \Rightarrow$  focusing/defocusing mKdV equation. Arises naturally in plasma physics as a model for ion acoustic perturbations.
- $f(u) = \alpha u^{r+1/2}$  for  $r \in (-\frac{1}{2}, \frac{1}{2})$ ... has been derived in several plasma physics models.

Also interesting for mathematical study:  $f(u) = u^5$  is  $L^2$  critical, and KdV and mKdV are completely integrable!

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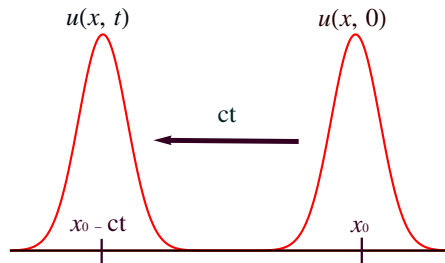
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- Consider traveling wave profile  $u(x, t) = u(x + ct)$ .
- Characteristics:
  - (1) Constant velocity  $c$
  - (2) Same shape and profile!



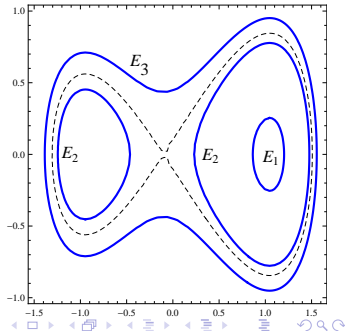
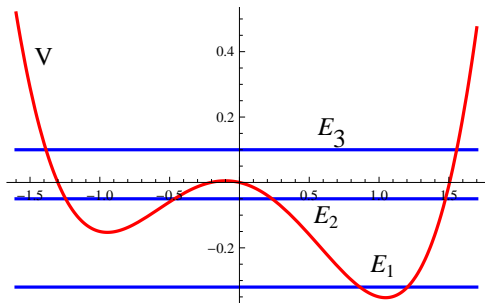
- Solution is STATIONARY solution of PDE

$$u_t = u_{xxx} + f(u)_x - cu_x.$$

- Wave profile  $u$  must satisfy ODE

$$u_{xxx} + f(u)_x - cu_x = 0$$

$$\Rightarrow \frac{u_x^2}{2} = E - \underbrace{F(u) - \frac{cu^2}{2} + au}_{V(u;a,c)}, \quad F' = f, \quad a, E \in \mathbb{R}.$$



- Periodic traveling waves form a four parameter family  $\mathcal{P}$  of solutions

$$u(x) = u(x + x_0; a, E, c)$$

- Translation mode can be modded out: Consider quotient space  $\mathcal{P}/\mathcal{R}$  where

$$u\mathcal{R}v \iff \exists \xi \in \mathbb{R} : u = v(\cdot + \xi).$$

Near any nonconstant solution then, the projection  $\mathcal{P} \mapsto \mathcal{P}/\mathcal{R}$  is locally a fibration (where the fibers are circles) and hence  $\mathcal{P}/\mathcal{R}$  is locally dimension three.

- **Henceforth**, we will identify  $\mathcal{P}$  and  $\mathcal{P}/\mathcal{R}$  and hence consider  $\mathcal{P}$  as a manifold of dimension three.

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- What one does see in experiment, however, are solutions which *locally in space-time* look spatially periodic, but on larger scales there is evident slow change in the physical characteristics of the wave (amplitude, frequency, phase, etc...).
- Thus, our spatially periodic solutions are *idealized* versions of these slowly modulated periodic waves!
- Q: How can one study the stability of these seemingly more physical nonlinear modulated waves?
- A: We treat them as perturbations of the idealized periodic solutions to slow modulations, ie. to long-wavelength perturbations.
- Q: OK..... how do we do that?!

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# Periodic Stability Theory

- Let  $u$  be  $T$ -periodic stationary solution of the nonlinear PDE

$$u_t = u_{xxx} + f(u)_x - cu_x.$$

Consider nearby solutions of form

$$\psi(x, t) = u(x) + \varepsilon v(x, t) + \mathcal{O}(\varepsilon^2), \quad v \in L^2(\mathbb{R}).$$

$$\Rightarrow \partial_x \underbrace{(-\partial_x^2 - f'(u) + c)}_{\mathcal{L}[u]} v = -v_t$$

Decompose  $v(x, t) = e^{-\mu t} v(x)$  so  $v$  solves the spectral problem

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considered on  $L^2(\mathbb{R})$ .

Spectral stability  $\iff \text{spec}(\partial_x \mathcal{L}[u]) \subset \mathbb{R}i$ .

- This is NOT an eigenvalue problem: Since the operator  $\partial_x \mathcal{L}[u]$  has periodic coefficients, it can not have decaying eigenfunctions! Thus, there are no  $L^2$  eigenvalues!!



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- To see this, write spectral problem as first order system

$$Y'(x, \mu) = \mathbf{H}(x, \mu)Y(x, \mu).$$

- Period Map (Monodromy):  $\mathbf{M}(\mu) = \Phi(T, \mu)$ , where  $\Phi(x, \mu)$  is the matrix solution such that  $\Phi(0, \mu) = \mathbf{I}$ . Thus,  $\mathbf{M}(\mu)$  is an operator such that

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for any  $x \in \mathbb{R}$  and vector solution  $v(x, \mu)$ . For simplicity, assume that  $v(x, \mu)$  satisfies

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Then for all  $n \in \mathbb{Z}$  have

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- Gives characterization of (continuous) spectrum:

$$\mu \in \text{spec}(\partial_x \mathcal{L}[u]) \iff \sigma(\mathbf{M}(\mu)) \cap S^1 \neq \emptyset.$$

Following Gardner then, we define

$$D(\mu, e^{i\kappa}) = \det(\mathbf{M}(\mu) - e^{i\kappa} \mathbf{I}).$$

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- How does all this help determine modulational stability?

“**FACT**”: Stability to slow-modulations equivalent with spectral stability near  $\mu = 0$ . Need to study  $\text{spec}(\partial_x \mathcal{L}[u])$  near the origin.

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- At  $\mu = 0$ ,  $\{u_x, u_a, u_E\}$  provides three linearly independent solutions of the *formal* differential equation

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Thus, can explicitly construct monodromy matrix at  $\mu = 0$ .

- By analyticity of  $\mathbf{M}(\mu)$ , have

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We use perturbation theory to find  $\mathbf{M}_\mu(\mu)$ ....

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Follows that  $-u_c$  gives first order  $\mu$ -variation in translation ( $u_x$ ) direction!!!! Thus, we have constructed  $\mathbf{M}_\mu(0)$ .

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# Asymptotic Expansion of $D(\mu, 1)$

- Taking determinants then, we have

$$\frac{d}{d\mu} D(\mu, 1) = \det (\mathbf{M}(0) + \mu \mathbf{M}_\mu(0) - I + \mathcal{O}(|\mu|^2)) \Big|_{\mu=0} = 0$$

⇒ Implicit Function Theorem fails!!!!

- We need to determine next order term  $\mathbf{M}_{\mu\mu}(0)$ . Can be done by using variation of parameters again!
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$$D(\mu, 1) = -\frac{1}{2} \underbrace{\frac{\partial(T, M, P)}{\partial(a, E, c)}}_{\{T, M, P\}_{a, E, c}} \mu^3 + \mathcal{O}(|\mu|^4).$$

where  $T$  = period and  $M$  and  $P$  refer to the mass and momentum:

$$M = \int_0^T u(x) dx \quad P = \int_0^T u(x)^2 dx$$

$M$  and  $P$  are conserved quantities of the gKdV flow!

- Thus,  $D(\mu, 1) = \mathcal{O}(|\mu|^3)$  and hence more care is needed to use the implicit function theorem.
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# Modulational Instability

- Continuing above computations, local analysis around  $(\mu, \kappa) = (0, 0)$  yields

$$D(\mu, e^{i\kappa}) = i\kappa^3 + \frac{i\kappa\mu^2}{2} (\{T, P\}_{E,c} + 2\{M, P\}_{a,E}) \\ - \frac{\mu^3}{2} \{T, M, P\}_{a,E,c} + \mathcal{O}(|\mu|^4 + \kappa^4)$$

where the notation  $\{f, g\}_{x,y}$  is used for two-by-two Jacobians.

- Defining  $z = \frac{i\kappa}{\mu}$ , we see  $z$  must be a root of

$$P(z) = -z^3 + \frac{z}{2} (\{T, P\}_{E,c} + 2\{M, P\}_{a,E}) - \frac{1}{2} \{T, M, P\}_{a,E,c}.$$

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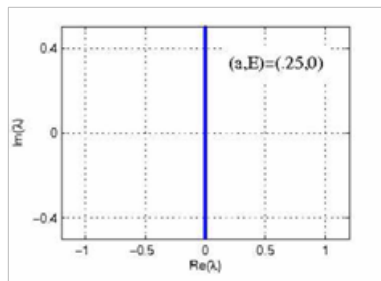
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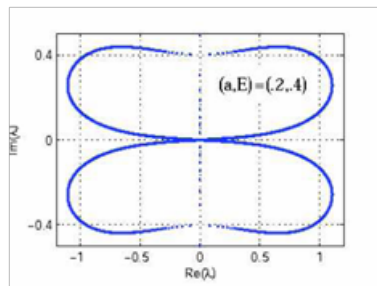
# Modulational Instability: M.J. & Bronski (2008)

Define

$$\Delta_{MI} := \frac{1}{2} (\{T, P\}_{E,c} + 2\{M, P\}_{a,E})^3 - \frac{27}{4} \{T, M, P\}_{a,E,c}^2.$$



$$\Delta_{MI} > 0$$



$$\Delta_{MI} < 0$$

# Whitham Theory

- Physicists have had a formal approach of such modulational stability arguments for years (at least 1973) which has been dubbed Whitham theory!
- Introduce slow variables  $\varepsilon x$  and  $\varepsilon t$  and note the idealized is constant in the slow variables.
- Consider the original PDE in the slow variables and linearize about the idealized constant solution... after averaging, yields a constant coefficient system of PDE!
- Expectation: The stability of the constant (idealized) solution in the averaged-slow variable system should appropriately describe the stability of the original modulated wave.
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# Whitham Theory for GKdV

- In slow variables, gKdV reads

$$u_t = \varepsilon^2 u_{xxx} + f(u)_x$$

Consider WKB approximation

$$u_\varepsilon(x, t) = u^0 \left( x, t, \frac{\phi(x, t)}{\varepsilon} \right) + \varepsilon u^1 \left( x, t, \frac{\phi(x, t)}{\varepsilon} \right) + \mathcal{O}(\varepsilon^2)$$

where  $y \rightarrow u^0(x, t, y)$  is an unknown 1-periodic function.

Substitute this into rescaled gKdV and collect powers of  $\varepsilon$ .

- $\mathcal{O}(\varepsilon^{-1})$ :  $\phi_x^3 \partial_y^3 u^0 + \phi_x \partial_y f(u^0) - \phi_x \partial_y u^0 = 0$ . Defining  $\omega = \phi_x$  and  $s = -\frac{\partial_t}{\partial_x}$ , may choose

$$u^0(x, t, y) = \bar{u}(\omega y; a(u^0), E(u^0), -s(u^0)), \quad \bar{u} \in \mathcal{P}$$

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From the gKdV we find that

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- With the addition of this extra conservation law, we now have three equations for the three dimensional unknown  $u^0 \in \mathcal{P}$ .
- Assuming  $(a, E, c)$  are good local coordinates on  $\mathcal{P}$ , we can write the Whitham system as

$$\partial_t (M\omega, P\omega, \omega) - \partial_x (a - sM\omega, -sP\omega - 2E, -s\omega) = 0$$

where now these are considered as functions of  $(a, E, s) \in \mathbb{R}$ .

- To determine the stability of a particular constant solution corresponding to  $(a, E, s) = (a_0, E_0, -c_0)$ , following the physicists intuition we linearize the above system at this point.



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- The resulting linear system is has constant coefficients, and hence we can determine its stability by Fourier Transform techniques: need the characteristic polynomial

$$P(\mu, \kappa) = \det \left( \mu \frac{\partial (M\omega, P\omega, \omega)}{\partial (a, E, s)} - \frac{i\kappa}{T} \frac{\partial (a - sM\omega, -sP\omega - 2E, -s\omega)}{\partial (a, E, s)} \right)$$

have three real roots in the variable  $\frac{i\kappa}{\mu T}$  at  $(a, E, s) = (a_0, E_0, -c_0)$ .

- Equivalent to hyperbolicity (i.e. local well-posedness) of Whitham system!
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# Whitham Theory Vs. Evans Function Techniques: M.J. & Zumbrun (2009)

- Direct (ugly) calculation shows that

$$D(\mu, e^{i\kappa}) = \Gamma_0 P(-\mu, \kappa) + \mathcal{O}(|\mu|^4 + \kappa^4)$$

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# Computation?

- OK, so you have an expression which “determines” when a particular wave is modulationally stable..... can you compute it?!
- YES!!!
  - (1) For power-law nonlinearities ( $f(u) = u^{p+1}$ ) with  $p \in \mathbb{N}$ , can determine explicit formula for MI index in terms of moments of the underlying wave.
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# Modulational Theory for KdV

- In case of KdV

$$u_t = u_{xxx} + \left(\frac{u^2}{2}\right)_x,$$

can express conserved quantities and period as integrals of closed cycles over a Riemann surface, and hence we can compute MI index using elliptic function calculations (Picard-Fuchs system).

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$$\Delta_{MI} = C_0 \cdot \frac{N^2}{\text{disc}(P(a, E, c))}$$

where  $C_0 > 0$  and

$$P(a, E, c) = E + au + \frac{c}{2}u^2 - \frac{u^3}{6}.$$

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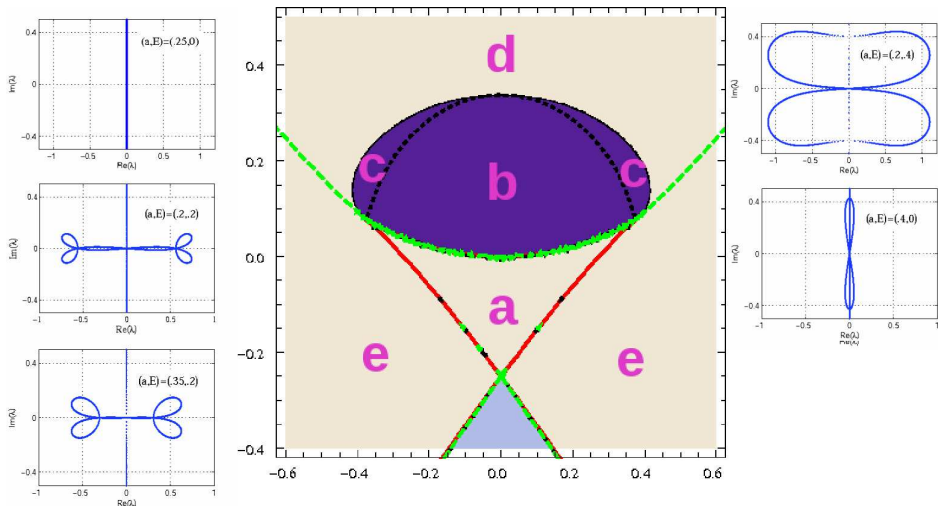
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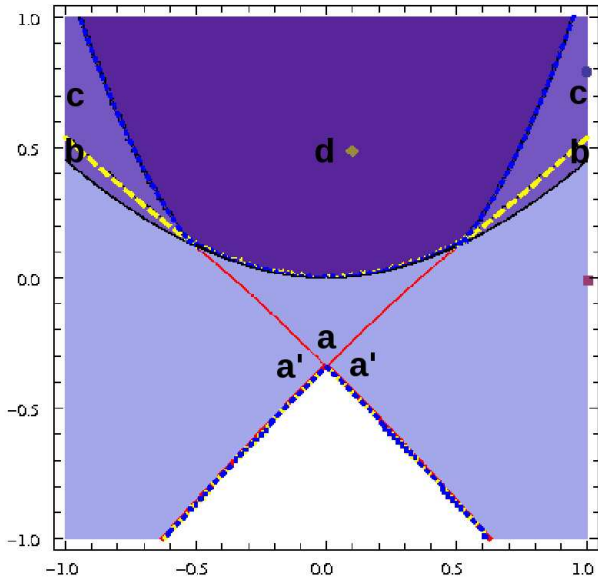
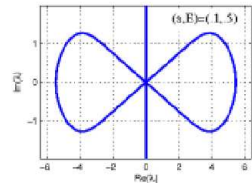
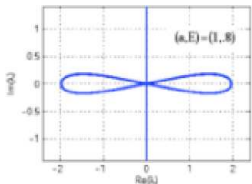
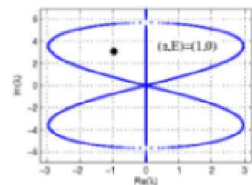
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# Modulational Theory for mKdV $f(u) = u^3$ (with positive wavespeed)



# $L^2$ -Critical KdV $f(u) = u^5$ (with positive wavespeed)



# Conclusions:

- Have extended modulation arguments of Whitham for KdV to non-zero mean waves of gKdV.
- Outline of Rigorous Theory: Integrability of traveling wave ODE  $\Rightarrow$  generalized null-space of linearized operator can be "explicitly computed". Once this is in hand, perturbation theory and elbow grease does the rest!
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